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**INTORQ**

setting the standard



## **BFK458 spring-applied brake**

The versatile modular system

1.5 – 600 Nm

[www.intorq.com](http://www.intorq.com)

## We set the standards

The INTORQ brand stands for reliable brake solutions with the highest product standards. INTORQ products are used in a very diverse range of applications, from brake motors and industrial trucks to hoists, cranes and wind turbines. We can create the right solution for you and your drive – individually and reliably.

The INTORQ module system offers numerous variants that can be used in many motors and geared motors, setting standards worldwide. We have been increasing our international presence step by step, establishing sites in Shanghai, Atlanta and Pune. So our network of sales and service staff is close at hand all over the world, ready to support you.



### INTORQ at a glance

- Electromagnetic brakes and clutches
- Flexibility with standard options as well as customised solutions
- Centralised product development and production located in aerzen
- Fast response and delivery times globally thanks to production and warehousing in Shanghai, Atlanta and Pune.
- Over 50 million euros a year sales volume
- 800,000 units a year
- 13,000 square metres production area
- 250 employees
- Market leader with 63 sales partners in 49 countries



## BFK458 – The modular system

This modular system forms the basis for a product range that offers versions tailored for almost any task. The BFK458 spring-applied brake, as a standard product, can be used anywhere, but its modular structure also meets the requirements of specific industries. Its strength lies in its versatility.

Electromagnetically released spring-applied brakes are used wherever masses in motion have to be decelerated as quickly as possible or where masses must be held in a defined position. The braking force is applied by tappet springs. Thus the braking torque generated by friction locking remains available in the deenergised status – even in the event of mains failure. The brake is released electromagnetically.

The main components of the modular system are the two basic modules E (adjustable braking torque) and N (non-adjustable braking torque).

The greatest degree of flexibility is achieved for a broad range of applications by combining the basic modules with specific modules. This catalogue is designed to assist you in selecting and ordering your desired spring-applied brake quickly and easily.

### Fields of application

- Brake motors
- Conveyors
- Cranes
- Storage technology
- Industrial trucks
- Wood working machines
- Stage machinery
- Vehicles for the disabled
- Automation technology
- Controlled drives
- Gate drives
- Escalators



Wind turbines



Cranes



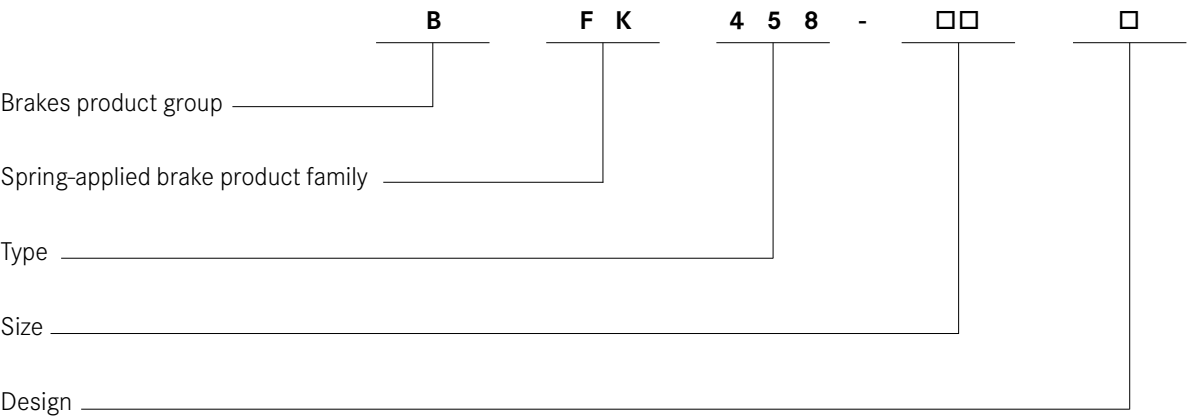
Industrial trucks



Stage machinery



INTORQ BFK458- product key



**Size**

06, 08, 10, 12, 14, 16, 18, 20, 25

Not coded:

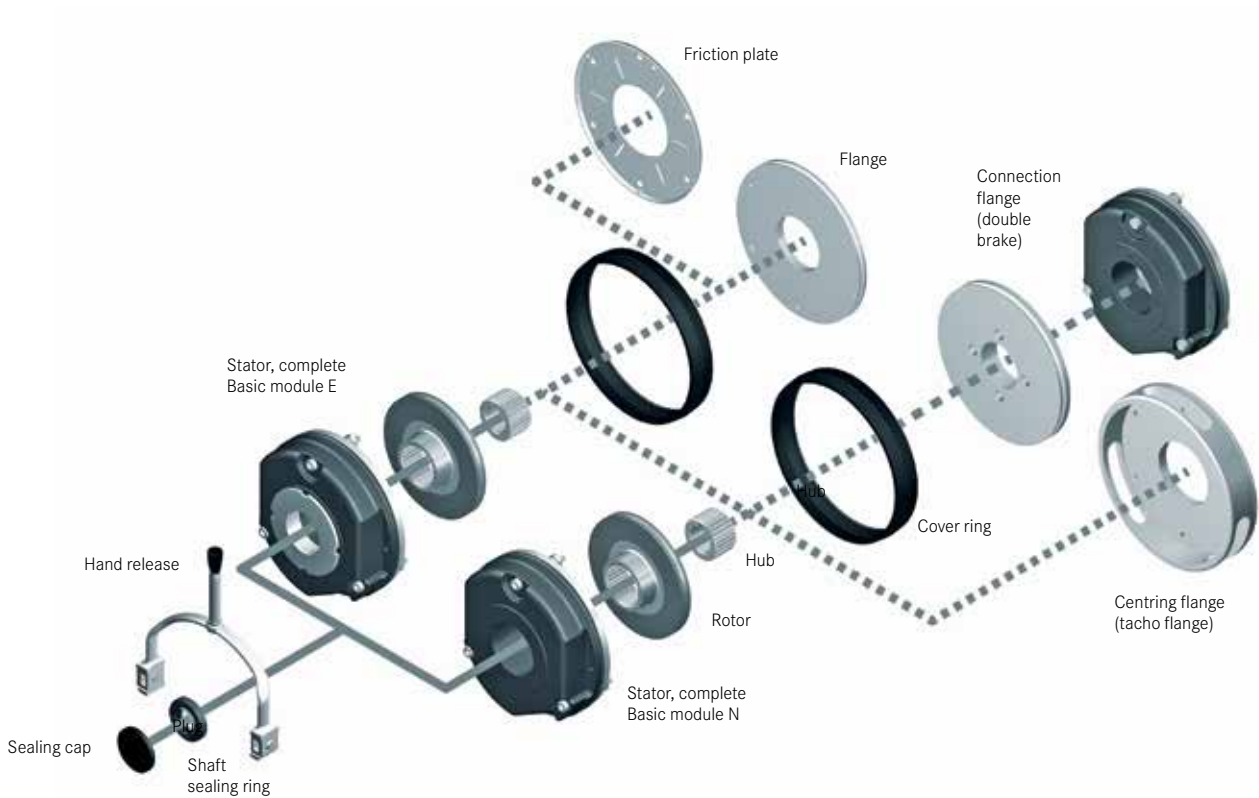
Supply voltage, hub bore, options

**Stator design**

E – Adjustable (braking torque can be reduced using torque adjustment ring)

N – Non-adjustable

L – Non-adjustable, LongLife design



# Contents

<b>Product key</b> .....	4	Brake cover.....	21
<b>List of abbreviations</b> .....	5	Microswitch .....	22
<b>Product information</b> .....	6	Terminal box .....	23
<b>Functional principle</b> .....	7	Rectifier type code .....	24
 <b>Technical data</b>		Spark suppressor 14.198.00 .....	24
Rated torques .....	8	Bridge rectifier + half-wave rectifier.....	25
Basic module E .....	10	Connection plans .....	29
Basic module N.....	12	Supply voltage selection table.....	31
2 x basic module N + connection flange .....	14	 <b>Dimensioning</b>	
Basic module N + tacho flange.....	15	Basics.....	32
Rated data .....	16	Example calculation .....	33
Operating times .....	16/17	 <b>Overview</b> .....	34
Service life and wear.....	18		
 <b>Accessories</b>			
Hand release/flange/friction plate .....	19		
Centring flange/connection flange/cover ring .....	20		

## List of abbreviations

<b>P<sub>N</sub></b>	[W]	Rated coil power at rated voltage and 20°C	<b>S<sub>hue</sub></b>	[1/h]	transitional operating frequency, thermal rating of the brake/clutch
<b>U<sub>N</sub></b>	[V DC]	Rated coil voltage	<b>S<sub>hmax</sub></b>	[1/h]	Maximum permissible operating frequency, depending on the friction work per operation
<b>M<sub>K</sub></b>	[Nm]	Rated torque of the brake at a relative speed of 100 r/min	<b>SLN</b>	[mm]	Rated air gap
<b>M<sub>dyn</sub></b>	[Nm]	dynamic brake torque, measured at constant speed of rotation	<b>SHL</b>	[mm]	Hand-release air gap, setting dimension of hand-release
<b>M<sub>L</sub></b>	[Nm]	Load torque, torque that the static load produces at the motor shaft	<b>t<sub>1</sub></b>	[s]	Engagement time, the total of the reaction delay and torque rise time $t_1 = t_{11} + t_{12}$
<b>Δn<sub>0</sub></b>	[r/min]	Initial relative speed of the brake	<b>t<sub>2</sub></b>	[s]	Disengagement time, time from switching the stator until the torque has reduced to 0.1 M <sub>K</sub>
<b>J<sub>L</sub></b>	[kgm <sup>2</sup> ]	moment of inertia of the load, referred to referred to the output shaft (load shaft)	<b>t<sub>3</sub></b>	[s]	Slipping time to standstill (after t <sub>11</sub> )
<b>Q</b>	[J]	Heat/energy	<b>t<sub>11</sub></b>	[s]	Delay time when connecting, time from disconnecting the voltage until the torque begins to rise
<b>Q<sub>E</sub></b>	[J]	Maximum permissible friction work per switching cycle, thermal rating of the brake	<b>t<sub>12</sub></b>	[s]	Rise time of braking torque, time from beginning of rise of torque until braking torque is reached
<b>Q<sub>smax</sub></b>	[J]	maximum permissible friction work during cyclic switching, depending on the operating frequency			
<b>S<sub>h</sub></b>	[1/h]	Operating frequency, the number of repeated operations per unit time			

## Product information



### A powerful and complete range

- 9 sizes
- Standard voltages [V DC] 24, 96, 103, 170, 180, 190, 205
- Graduated torque range from 1.5 – 600 Nm
- Short delivery times for the complete range thanks to optimised logistics
- Enclosure according to IP00 ... IP55, depending on the special operating conditions, see technical data sheet
- **ATEX:** In accordance with Group II, Category 3G/D, the product is suitable for use in potentially explosive atmosphere of zone 2 (gases and vapours) and zone 22 (dust) for steady-state operation (holding or parking brake) and temperature class T4.

### Versatile

- Modular structure for virtually all applications

### Torque transmission

- Designed for dry running

### Quick and easy mounting

- Preset air gap
- Special machining of the friction surfaces ensures that the rated torques are achieved after very few switching operations
- No locating bearing is required on the brake

### Durable

- The insulation system to temperature class F (155°C) ensures that the winding has a long service life
- The brakes are designed for 100% duty time (current applied to the brake)

### Low maintenance

- Long rotor/hub connection with low rate of wear and a tried-and-tested involute gear
- Asbestos-free and solvent-free friction lining with low rate of wear

### Reliable

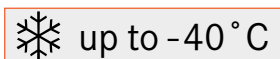
- The certified ISO 9001 and ISO 14001 quality assurance system provides the basis for consistently high-quality products
- Production and testing to VDE 0580

### Options

- Hand release for all sizes, both directions can be used for release and mounting (exception: tachometer brake)
- Noise-reduced designs
- Various types of corrosion protection and enclosures
- Microswitches used to monitor air gap and wear (size 12 and above)
- Monitoring of Hand release function
- Non-standard voltages and bores on request
- Pulse width modulation (PWM), sizes 06 – 18
- Partial discharge free brake has been developed for operation with the pulse width modulated DC bus voltage of a frequency inverter
- Rated coil voltage  $U_N=103V$  DC

### LongLife design BFK458-L

- Armature plate with low backlash and reinforced torque support
- Tappet springs with guide pins for protection against shearing forces
- Aluminium rotor with toothed intermediate ring: friction lining and tooth system with low rates of wear

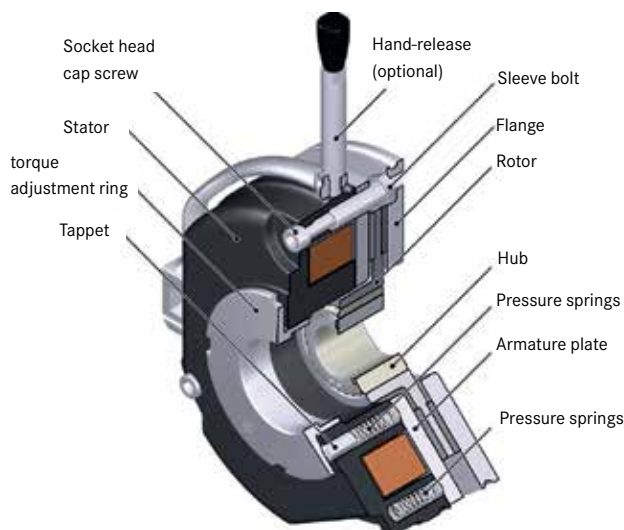


### CCV (Cold Climate Version), temperature-resistant up to -40 °C

- CCV design configurable for all sizes in the modular system
  - Use of chrome-plated friction surfaces (armature plate and flange)
- The following components are also approved for use up to -40 °C
  - Rotor with sleeve (noise-reduced)
  - Hand release
  - Terminal box
  - Microswitch
  - Caps E and N
  - Shaft sealing rings (available on request)

# Functional principle

## Basic module E



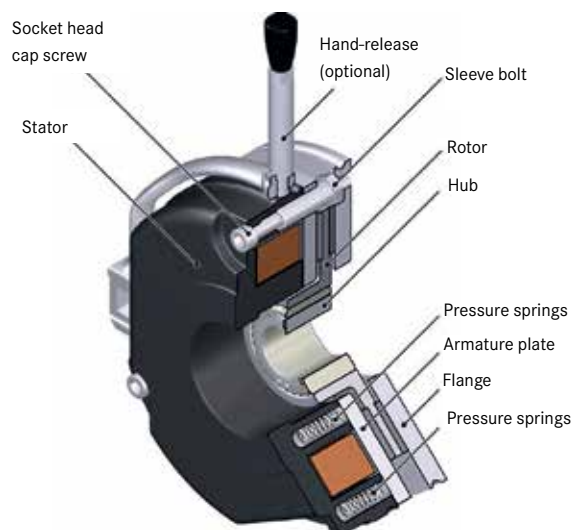
The brake is an electrically releasable spring-applied brake with a rotating braking disk (rotor) that is equipped with friction linings on both sides. In a de-energised state, the rotor is stretched between the armature plate and a counter friction face by a normal brake force that is produced by pressure springs. The function thus corresponds to the failsafe principle. The braking torque that is applied to the rotor is transmitted via an axially toothed hub to the input shaft.

The brake can be used as a holding brake, as an operating brake and for emergency stops from a high speed.

The asbestos-free friction linings ensure a safe braking torque and low wear. In addition to the powerful standard friction lining, there are also special friction linings for a range of different applications, e.g. with high wear resistance or an increased friction coefficient.

To release the brake, the armature plate is lifted electromagnetically from the rotor. The rotor, shifted axially and balanced by the spring force, can turn freely.

## Basic module N



### Project planning notes

- When designing a brake for specific applications, torque tolerances, the limiting speeds of the rotors, the thermal resistance of the brake, and the effect of environmental influences must be taken into account.
- The brakes are designed so that the stated rated torques can normally be safely achieved after a short run-in period.
- As a result of the fluctuating properties of the organic friction linings and changing environmental conditions, however, deviations in the stated torques can occur. These deviations should be taken into account in the dimensioning by means of relevant safety measures. Especially when there is dampness and changing temperatures, an increase in breakaway torque can occur after periods of non-operation.
- When the brake is used purely as a holding brake without any dynamic load, the friction lining must be reactivated at regular intervals.

### Reducing braking torque

Basic module E: unscrewing the centrally located torque adjustment ring can reduce the spring force and, with it, the braking torque.

## Technical data

### Rated torques

The basic modules E and N are available in the graduated torques listed below. A pole shim (brass film) must be placed between the stator and the armature plate if you want to achieve short engagement times at low torques. INTORQ brakes are dimensioned so that the specified rated torques can usually be achieved reliably after a short running-in period. However, as the organic friction linings used do not all have identical properties and because environmental conditions can vary, deviations from the specified braking


torques are possible. These must be taken into account in the form of appropriate dimensioning tolerances. Increased breakaway torque is common in particular after long downtimes in humid environments where temperatures vary. If the brake is being used on friction surfaces provided by the customer, the rated torque must be checked. If the brake is to be used solely as a holding brake without dynamic load, the friction lining must be reactivated at regular intervals.


Size	06	08	10	12	14	16	18	20	25
Rated torque $M_K$ [Nm] of the brake, rated value at a relative speed of 100 r/min								80 E	
	1.5 E	3.5 N/E/L			25 N/E	35 N/E	65 N/E	115 N/E	175 N/E
	2 N/E/L	4 E	7 N/E/L	14 N/E/L	35 N	45 N/E	80 N/E	145 N/E	220 N
	2.5 N/E/L	5 N/E/L	9 N/E/L	18 N/E/L	40 N/E	55 N/E	100 N/E	170 N/E	265 N/E
	3 N/E/L	6 N/E/L	11 N/E/L	23 N/E/L	45 N/E	60 N/E	115 N/E	200 N/E	300 N/E
	3.5 N/E/L	7 N/E/L	14 N/E/L	27 N/E/L	55 N/E	70 N/E	130 N/E	230 N/E	350 N/E
	<b>4 N/E/L</b>	<b>8 N/E/L</b>	<b>16 N/E/L</b>	<b>32 N/E/L</b>	<b>60 N/E</b>	<b>80 N/E</b>	<b>150 N/E</b>	<b>260 N/E</b>	<b>400 N/E</b>
	4.5 N/E	9 N/E	18 N/E	36 N/E	65 N/E	90 N/E	165 N/E	290 N/E	445 N/E
	5 E	10 E	20 E	40 E	75 N/E	100 N/E	185 N/E	315 N/E	490 N/E
	5.5 E	11 E	23 N/E	46 N/E	80 N/E	105 N/E	200 N/E	345 N/E	530 N/E
	6 N/E	12 N/E				125 N/E	235 N/E	400 N/E	600 N/E


■ N ... Braking torque for the N design  
(without torque adjustment ring)

■ E ... Braking torque for the E design  
(with torque adjustment ring)

■ L ... LongLife design

 Operating brake  
( $s_{Lmax}$  approx.  $2.5 \times s_{LN}$ )

 Standard braking torque

 Holding brake with emergency  
stop ( $s_{Lmax}$  approx.  $1.5 \times s_{LN}$ )

### Basic module L, LongLife design

The LongLife design can be configured for sizes 06 to 12 in combination with the specified rated torques in the modular system. The stator corresponds to design N; bores and built-on accessories are not possible at the rear side. It is not possible to configure a microswitch for size 12.



### Basic module E, reduced rated torque

The rated torque on basic module E can be reduced using the torque adjustment ring located in the stator. The torque adjustment ring may only be unscrewed to a maximum dimension of  $h_{1\max}$  (see table on page 11).

It should be noted that the engagement and disengagement times change in accordance with the rated torque. Torque reduction is independent of the rated torque used.

Size	06	08	10	12	14	16	18	20	25
Torque reduction per detent position [Nm]	0.2	0.35	0.8	1.3	1.7	1.6	3.6	5.6	6.2

## Friction lining variants

### Standard and wear-resistant linings

The listed torque ratings and permissible friction work can be combined with any of the brake design options. The catalogue variants are available from a quantity of 1 up to series production levels.

#### ST (Standard)

- For universal use
- Large speed range
- Short run-in process required
- Can be used as holding brakes or operating brakes

#### WR (wear-resistant)

- Long service life
- Can be used in standard applications
- Restricted maximum speed
- Short run-in process required
- Best for use as an operating brake

### Project solutions

For project solutions INTORQ develops customised series production products on the basis of the customer's technical specifications. The following friction lining qualities are available for project solutions in addition to the catalogue variants:

#### HFC (high friction coefficient)

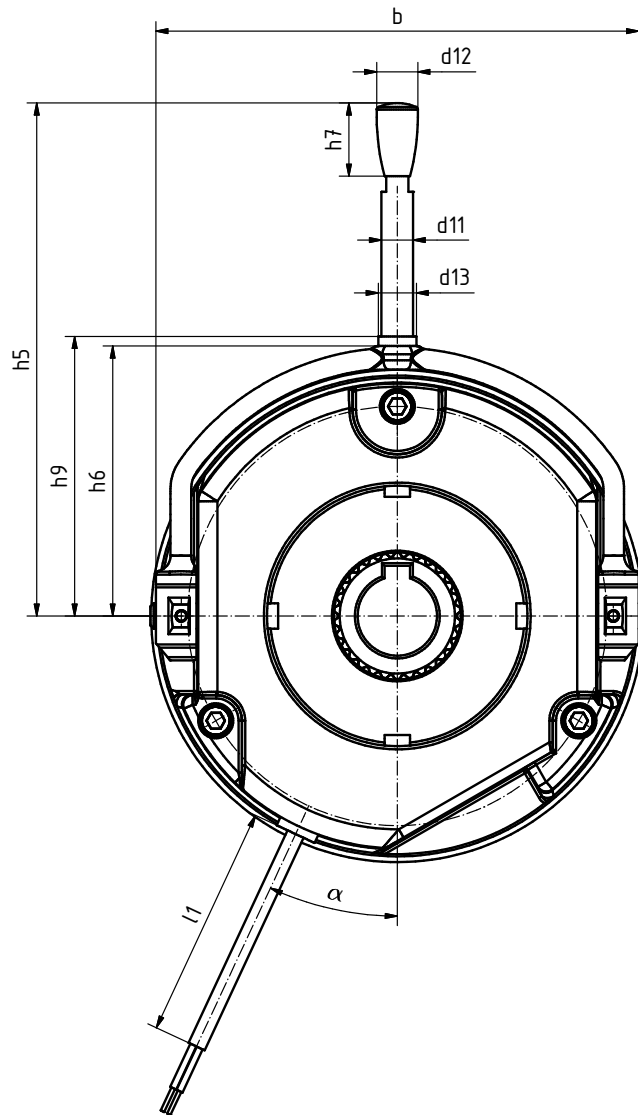
- For higher braking torques
- For use as a holding brake
- Short run-in process required

#### HT (high temperature)

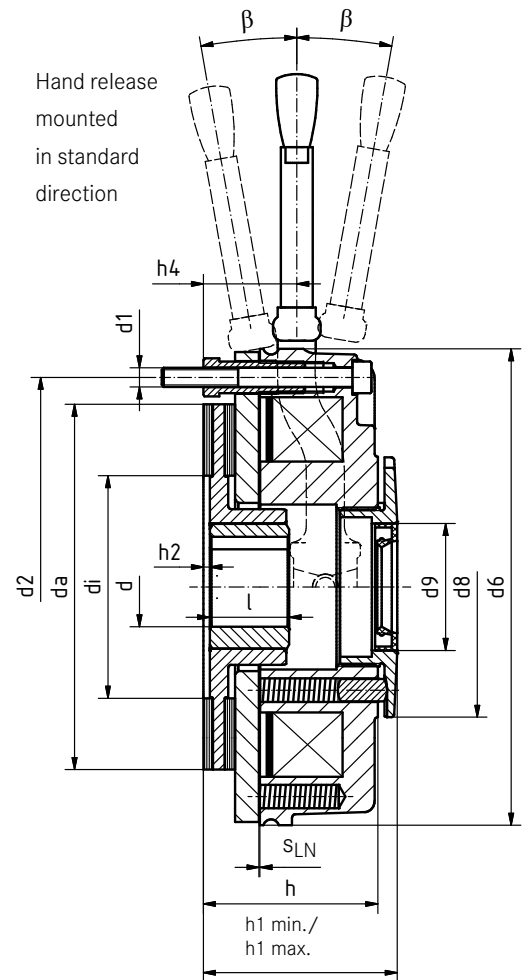
- Friction lining resistant to high temperatures to allow friction work up to a factor of 5 (compared with the standard aluminium rotor)
- Stable static torque
- Resistant to the effects of dampness and humidity

## Technical data

### Basic module E (with torque adjustment ring)



### Without counter friction surface, hand release (as option)



Size	b	d <sub>17</sub> 1) spec.	d <sub>H7 2)</sub> standard	d <sub>1</sub>	d <sub>2</sub>	d <sub>5</sub>	d <sub>6/7</sub>	d <sub>7</sub>	d <sub>8</sub>	d <sub>9</sub>	d <sub>10</sub>	d <sub>11</sub>	d <sub>12</sub>	d <sub>13</sub>	d <sub>16</sub>	d <sub>17</sub>	d <sub>18</sub>	d <sub>i</sub>	d <sub>a</sub>
06	88	10	10/11/12/14/15	3xM4	72	91	87	87	52	24 H9	31	8	13	9.6	3x4.4	86	36	40	60
08	106.5	10	11/12/14/15/20	3xM5	90	109	105	105	60	26 H9	41	8	13	9.6	3x5.5	106	45	56.1	76.5
10	132	10	11/12/14/15/20	3xM6	112	135.4	130	130	68	35 H9	45	10	13	12	3x6.6	132	52	66.1	95
12	152	14	20/25	3xM6	132	155	150	150	82	40 H9	52	10	13	12	3x6.6	153	68	70.1	115
14	169	14	20/25/30	3xM8	145	171	165	165	92	52 H9	55	12	24	14	3x9	169	78	80.1	124
16	187.6	15	25/30/35/38 <sup>3)</sup>	3xM8	170	196	190	190	102	52 H9	70	12	24	14	3x9	194	90	104.1	149
18	218.6	20	30/35/40/45	6xM8	196	223	217	217	116	62 H9	77	14	24	15	4x9 <sup>6)</sup>	-	-	129.1	174
20	252.6	25	35/40/45/50	6xM10	230	259	254	254	135	72 H8	90	14	24	17	4x11 <sup>6)</sup>	-	-	148.1	206
25	297.6	30	40/45/50/55/60/65/70 <sup>3)</sup>	6xM10	278	308	302	302	165	85 H8	120	16	24	18.4	6x11	-	-	199.1	254

<sup>1)</sup> Pilot bored without keyway

<sup>2)</sup> Standard keyway in accordance with DIN 6885/1 P9, selection of the shaft diameter dependent upon type of load (see the operating instructions)

<sup>3)</sup> Ø 38 and Ø 70 mm, keyway in accordance with DIN 6885/3 P9

<sup>4)</sup> Hand release angle tolerance +3°

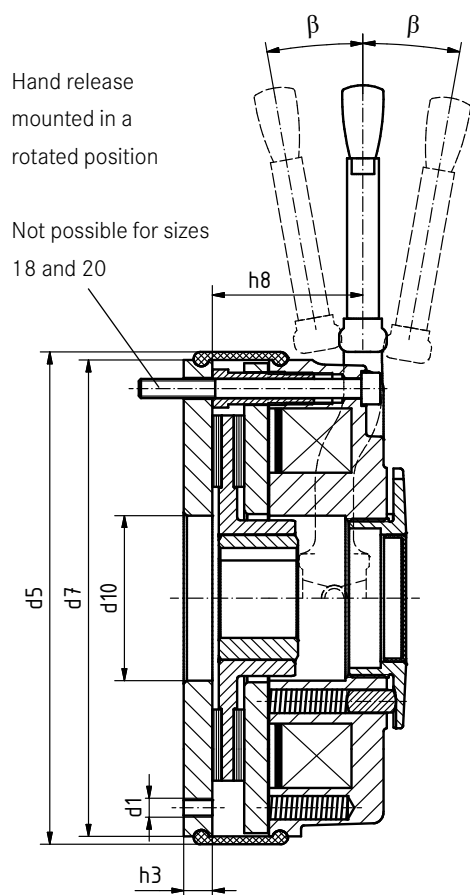
<sup>5)</sup> Recommended lever length for 1.5 M<sub>K</sub>

<sup>6)</sup> The thread in the mounting surface is offset by 30° in relation to the centre axis of the manual release lever

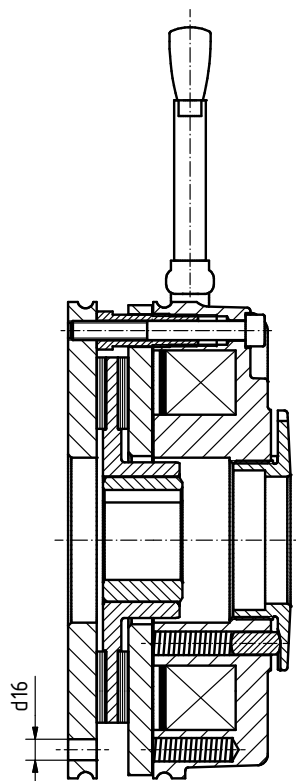
Recommended ISO shaft tolerances: up to Ø 50 mm = k6  
over Ø 50 mm = m6

Dimensions in mm

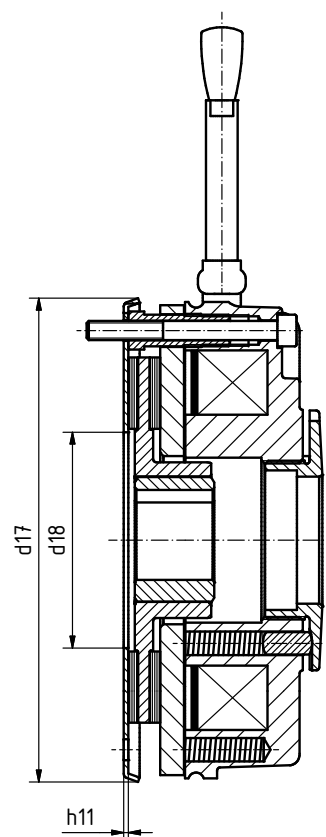
**With flange, hand release and seal ring (as option)**



**With flange, hand release (as option), mounted on flange**



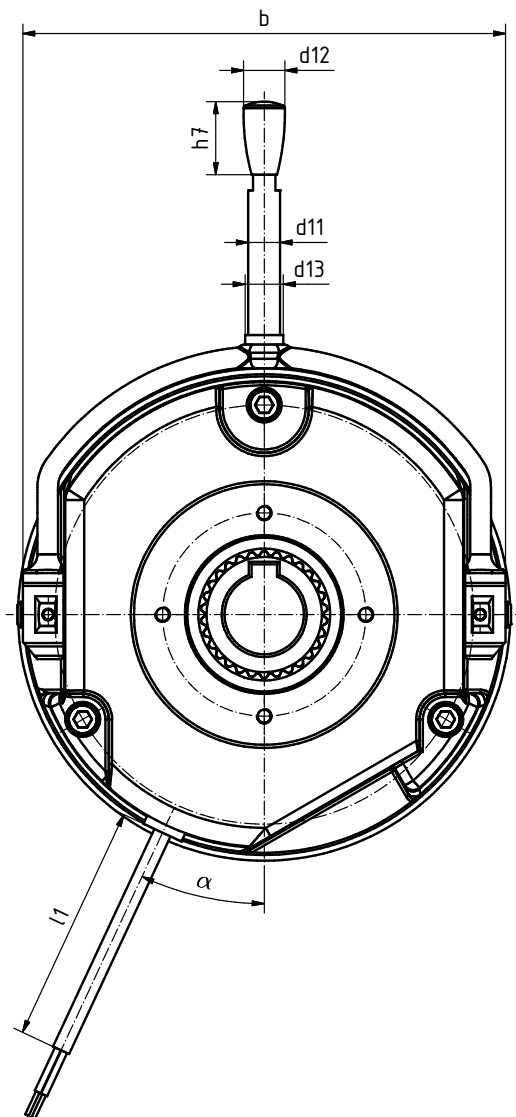
**With friction plate, hand release (as option)**



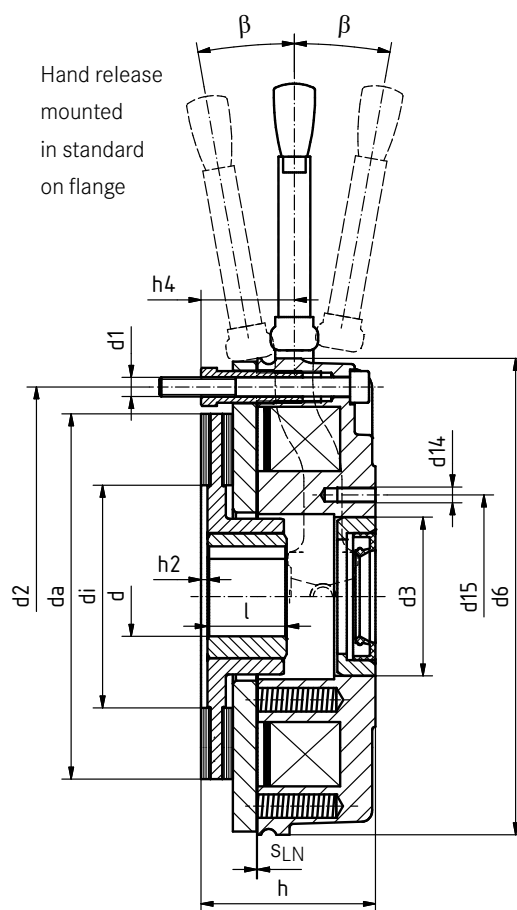
Size	h	h <sub>1</sub> min.	h <sub>1</sub> max.	h <sub>2</sub>	h <sub>3</sub>	h <sub>4</sub>	h <sub>5</sub> standard	h <sub>5</sub> <sup>5)</sup> max.	h <sub>6</sub>	h <sub>7</sub>	h <sub>8</sub>	h <sub>9</sub>	h <sub>11</sub>	l	l <sub>1</sub>	s <sub>LN</sub>	α	β <sup>4)</sup>
06	36.3	39.3	43.2	1	6	15.8	107	-	54	23	32.8	56	1.5	18	400	0.2	25°	10°
08	42.8	46.8	50.8	1	7	16.3	116	-	63	23	41.3	65	1.5	20	400	0.2	25°	10°
10	48.4	52.4	55.9	2	9	27.4	132	-	73.3	23	42.4	77.8	1.5	20	400	0.2	25°	10°
12	54.9	58.9	67.5	2	9	29.4	161	-	85	23	47.4	88	1.5	25	400	0.3	25°	10°
14	66.3	71.3	77.3	2	11	33.8	195	-	97.9	32	50	101	1.5	30	400	0.3	25°	10°
16	72.5	77.5	85.5	2.25	11	37	240	-	111	32	53.5	114	1.5	30	600	0.3	25°	10°
18	83.1	89.1	97.1	3	11	41.6	279	394	125	32	59.1	128	-	35	600	0.4	25°	10°
20	97.6	104.6	114.6	3.5	11	48.1	319	416	146	32	68.6	148.5	-	40	600	0.4	25°	10°
25	106.7	115.7	127.7	4.5	12.5	57.7	445	501	170	32	88.7	175	-	50	600	0.5	25°	10°

## Technical data

### Basic module N (without torque adjustment ring)



### Without counter friction face, hand release (as option)



Size	b	d1 <sup>1)</sup> spec.	dH7 <sup>2)</sup> standard	d1	d2	d3H7	d5	d6j7	d7	d10	d11	d12	d13	d14 <sup>4)</sup>	d15	d16	d17	d18	di	da
06	88	10	10/11/12/14/15	3xM4	72	25	91	87	87	31	8	13	9.6	4xM4	37.7	3x4.4	86	36	40	60
08	106.5	10	11/12/14/15/20	3xM5	90	32	109	105	105	41	8	13	9.6	4xM5	49	3x5.5	106	45	56.1	76.5
10	132	10	11/12/14/15/20	3xM6	112	42	135	130	130	45	10	13	12	4xM5	54	3x6.6	132	52	66.1	95
12	152	14	20/25	3xM6	132	50	155	150	150	52	10	13	12	4xM5	64	3x6.6	153	68	70.1	115
14	169	14	20/25/30	3xM8	145	60	171	165	165	55	12	24	14	4xM6	75	3x9	169	78	80.1	124
16	187.6	15	25/30/35/38 <sup>3)</sup>	3xM8	170	68	196	190	190	70	12	24	14	4xM6	85	3x9	194	90	104.1	149
18	218.6	20	30/35/40/45	6xM8	196	75	223	217	217	77	14	24	15	4xM8	95	4x9 <sup>7)</sup>	-	-	129.4	174
20	252.6	25	35/40/45/50	6xM10	230	85	259	254	254	90	14	24	17	4xM10	110	4x11 <sup>7)</sup>	-	-	148.1	206
25	297.6	30	40/45/50/55/60/65/70 <sup>3)</sup>	6xM10	278	115	308	302	302	120	16	24	18.4	4xM10	140	6x11	-	-	199.1	254

<sup>1)</sup> Pilot bored without keyway

<sup>2)</sup> Standard keyway in accordance with DIN 6885/1 P9, selection of the shaft diameter dependent upon type of load (see the operating instructions)

<sup>3)</sup> Ø 38 and Ø 70 mm, keyway in accordance with DIN 6885/3 P9

<sup>4)</sup> Bores are made on customer request for sizes 06 - 12

<sup>5)</sup> Hand release angle tolerance +3°

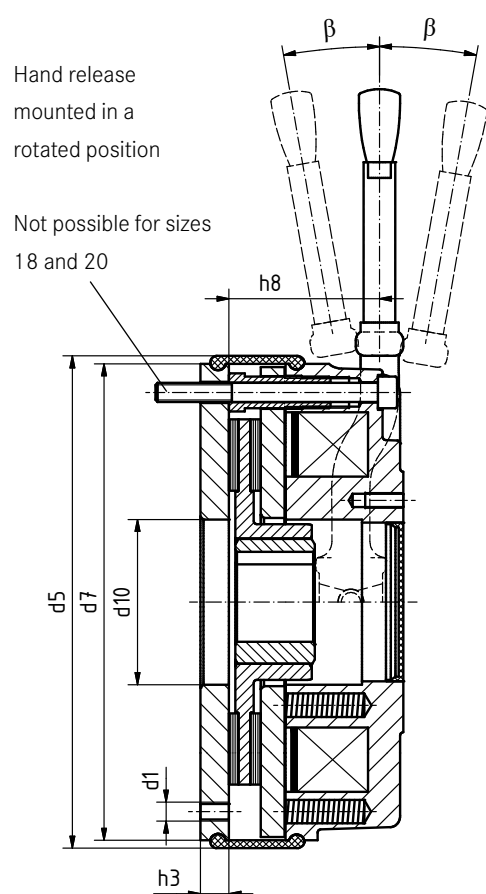
<sup>6)</sup> Recommended lever length for 1.5 M<sub>k</sub>

<sup>7)</sup> The thread in the mounting surface is offset by 30° in relation to the centre axis of the manual release lever

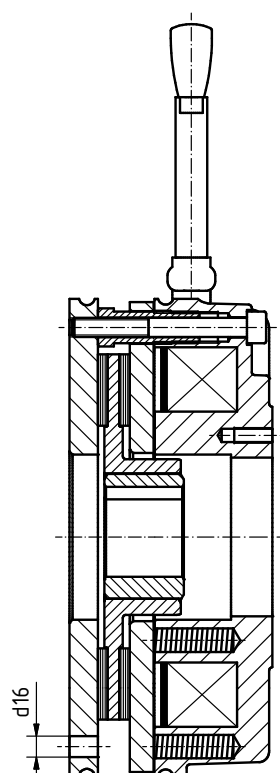
Recommended ISO shaft tolerances: up to Ø 50 mm = k6  
over Ø 50 mm = m6

Dimensions in mm

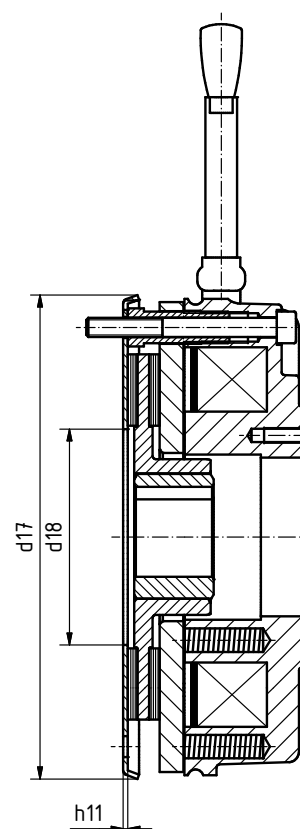
**With flange, hand release and seal ring (as option)**



**With flange, hand release (as option), mounted on flange**



**With friction plate, hand release (as option)**



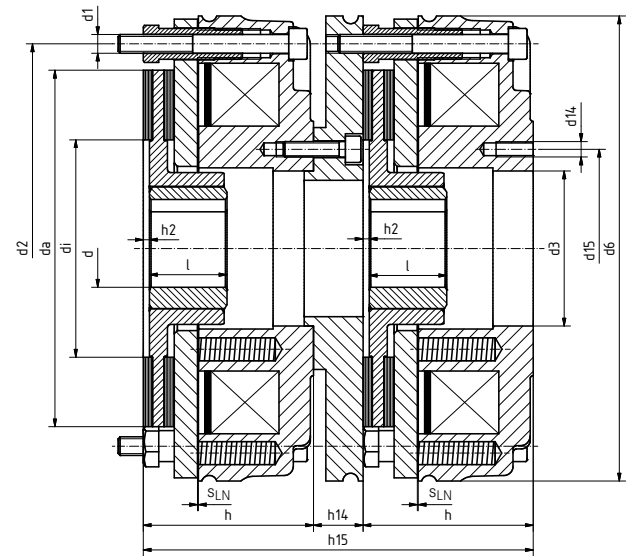
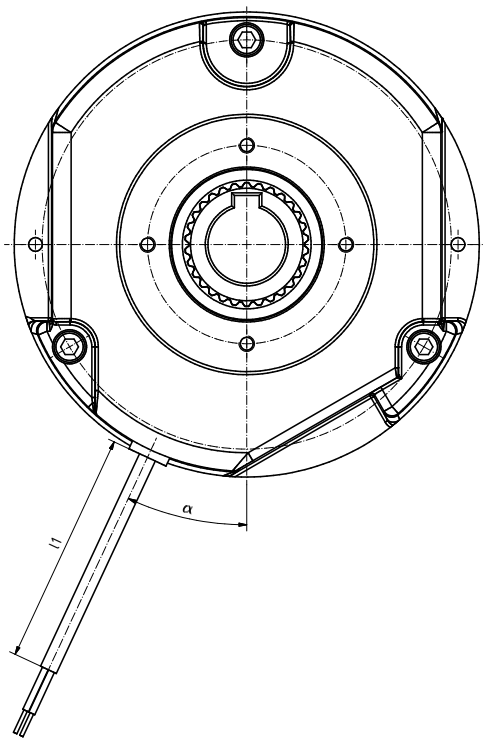
Size	h	h <sub>2</sub>	h <sub>3</sub>	h <sub>4</sub>	h <sub>5</sub> standard	h <sub>5</sub> <sup>6)</sup> max.	h <sub>6</sub>	h <sub>7</sub>	h <sub>8</sub>	h <sub>9</sub>	h <sub>11</sub>	l	l <sub>1</sub>	sLN	α	β <sup>5)</sup>
06	36.3	1	6	15.8	107	-	54	23	32.8	56	1.5	18	400	0.2	25°	10°
08	42.8	1	7	16.3	116	-	63	23	41.3	65	1.5	20	400	0.2	25°	10°
10	48.4	2	9	27.4	132	-	73.3	23	42.4	77.8	1.5	20	400	0.2	25°	10°
12	54.9	2	9	29.4	161	-	85	23	47.4	88	1.5	25	400	0.3	25°	10°
14	66.3	2	11	33.8	195	-	97.9	32	50	101	1.5	30	400	0.3	25°	10°
16	72.5	2.25	11	37	240	-	111	32	53.5	114	1.5	30	600	0.3	25°	10°
18	83.1	3	11	41.6	279	394	125	32	59.1	128	-	35	600	0.4	25°	10°
20	97.6	3.5	11	48.1	319	416	146	32	68.6	148.5	-	40	600	0.4	25°	10°
25	106.7	4.5	12.5	57.7	445	501	170	32	88.7	175	-	50	600	0.5	25°	10°



## Technical data

### 2 x basic module N + connection flange

Double brake as redundant braking system, suitable for use in stage machinery and many other areas of application. Available with hand release as an option.



Size	d <sub>J7</sub> <sup>1)</sup> spec.	d <sub>H7</sub> <sup>2)</sup> standard	d <sub>1</sub>	d <sub>2</sub>	d <sub>3H7</sub>	d <sub>6J7</sub>	d <sub>14</sub>	d <sub>15</sub>	d <sub>i</sub>	d <sub>a</sub>	h	h <sub>2</sub>	h <sub>14</sub>	h <sub>15</sub>	l	l <sub>1</sub>	s <sub>LN</sub>	α
06	10	10/11/12/14/15	3xM4	72	25	87	4xM4	37.7	40	60	36.3	1	12	84.6	18	400	0.2	25°
08	10	11/12/14/15/20	3xM5	90	32	105	4xM5	49	56.1	76.5	42.8	1	12	97.6	20	400	0.2	25°
10	10	11/12/14/15/20	3xM6	112	42	130	4xM5	54	66.1	95	48.4	2	13	109.8	20	400	0.2	25°
12	14	20/25	3xM6	132	50	150	4xM5	64	70.1	115	54.9	2	16	125.8	25	400	0.3	25°
14	14	20/25/30	3xM8	145	60	165	4xM6	75	80.1	124	66.3	2	17	149.6	30	400	0.3	25°
16	15	25/30/35/38 <sup>3)</sup>	3xM8	170	68	190	4xM6	85	104.1	149	72.5	2.25	20	165	30	600	0.3	25°
18	20	30/35/40/45	6xM8	196	75	217	4xM8	95	129.4	174	83.1	3	20	186.2	35	600	0.4	25°
20	25	35/40/45/50	6xM10	230	85	254	4xM10	110	148.1	206	97.6	3.5	20	215.2	40	600	0.4	25°
25	30	40/45/50/55/60/65/70 <sup>3)</sup>	6xM10	278	115	302	4xM10	140	199.1	254	106.7	4.5	25	238.4	50	600	0.5	25°

<sup>1)</sup> Pilot bored without keyway

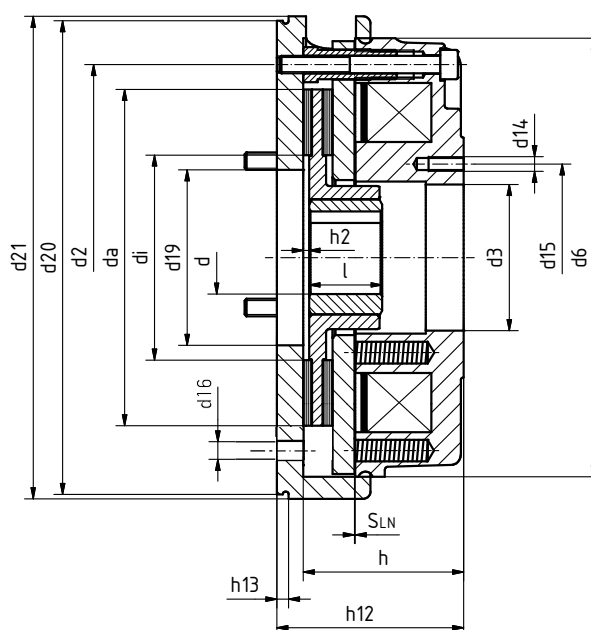
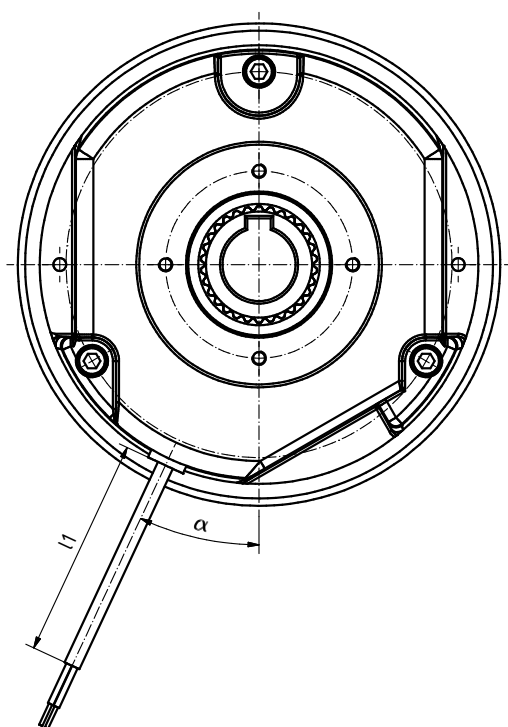
<sup>2)</sup> Standard keyway in accordance with DIN 6885/1 P9, selection of the shaft diameter dependent upon type of load (see the operating instructions)

<sup>3)</sup> Ø 38 and Ø 70 mm, keyway in accordance with DIN 6885/3 P9

Dimensions in mm

# Technical data

## Basic module N + tachometer flange



Size	dJ7 <sup>1)</sup> spec.	dH7 <sup>2)</sup> standard	d <sub>2</sub>	d <sub>3H7</sub>	d <sub>6J7</sub>	d <sub>14</sub>	d <sub>15</sub>	d <sub>16</sub>	d <sub>19h7</sub>	d <sub>20h7</sub>	d <sub>21</sub>	d <sub>i</sub>	d <sub>a</sub>	h	h <sub>2</sub>	h <sub>12</sub>	h <sub>13</sub>	l	l <sub>1</sub>	s <sub>LN</sub>	α
06	10	10/11/12/14/15	72	25	87	4xM4	37,7	3x4,4	40	95	98	40	60	36,3	1	42,3	4	18	400	0,2	25°
08	10	11/12/14/15/20	90	32	105	4xM5	49	3x5,5	50	115	116	56,1	76,5	42,8	1	49,8	4	20	400	0,2	25°
10	10	11/12/14/15/20	112	42	130	4xM5	54	3x6,6	60	140	141	66,1	95	48,4	2	57,4	4	20	400	0,2	25°
12	14	20/25	132	50	150	4xM5	64	3x6,6	60	162	165	70,1	115	54,9	2	63,9	4	25	400	0,3	25°
14	14	20/25/30	145	60	165	4xM6	75	3x9	80	177	181	80,1	124	66,3	2	77,3	4	30	400	0,3	25°
16	15	25/30/35/38 <sup>3)</sup>	170	68	190	4xM6	85	3x9	85	204	206	104,1	149	72,5	2,25	83,5	4	30	600	0,3	25°
18	20	30/35/40/45	196	75	217	4xM8	95	4x9 <sup>4)</sup>	90	233	237	129,4	174	83,1	3	94,1	4	35	600	0,4	25°
20	25	35/40/45/50	230	85	254	4xM10	110	4x11 <sup>4)</sup>	90	271	274	148,1	206	97,6	3,5	108,6	4	40	600	0,4	25°
25	30	40/45/50/55/60/65/70 <sup>3)</sup>	278	115	302	4xM10	140	6x11	120	322	324	199,1	254	106,7	4,5	119,2	4	50	600	0,5	25°

<sup>1)</sup> Pilot bored without keyway

<sup>2)</sup> Standard keyway in accordance with DIN 6885/1 P9, selection of the shaft diameter dependent upon type of load (see the operating instructions)

<sup>3)</sup> Ø 38 and Ø 70 mm, keyway in accordance with DIN 6885/3 P9

<sup>4)</sup> The thread in the mounting surface is offset by 30° in relation to the centre axis of the manual release lever

Dimensions in mm

Technical data

Rated data

Size	$P_N$ [W]	$S_{LNmax}$	$S_{Lmax}$	max.	min. <sup>2)</sup>	$J_{alurotor}$	Mass stator
	[at 20°C] <sup>1)</sup>	Operating brake [mm]	Holding brake [mm]	Adjustment [mm]	Rotor thickness [mm]	[kgcm <sup>2</sup> ]	compl. [kg]
06	20	0.5	0.3	1.5	4.5	0.15	0.75
08	25	0.5	0.3	1.5	5.5	0.61	1.2
10	30	0.5	0.3	1.5	7.5	2.0	2.1
12	40	0.75	0.45	2.0	8.0	4.5	3.5
14	50	0.75	0.45	2.5	7.5	6.3	5.2
16	55	0.75	0.45	3.5	8.0	15	7.9
18	85	1.0	0.6	3.0	10.0	29	12
20	100	1.0	0.6	4.0	12.0	73	19.3
25	110	1.25	0.75	4.5	15.5	200	29.1

<sup>1)</sup> Coil power at 20 °C in watts, deviation of up to ±10% possible dependent on the selected coil voltage.

<sup>2)</sup> The friction lining is dimensioned so that the brake can be readjusted at least five times

Rated torques

Size	Rated torque $M_K$ [Nm] [100 r/min]	Reduction of rated torque at specified speed to x%			Maximum speed $n_{max}$ [r/min]
		1500 r/min	3000 r/min	max.	
06	4	87%	80%	74%	6000
08	8	85%	78%	73%	5000
10	16	83%	76%	73%	4000
12	32	81%	74%	73%	3600
14	60	80%	73%	72%	3600
16	80	79%	72%	70%	3600
18	150	77%	70%	68%	3600
20	260	75%	68%	66%	3600
25	400	73%	66%	66%	3000

As speed increases, so does wear

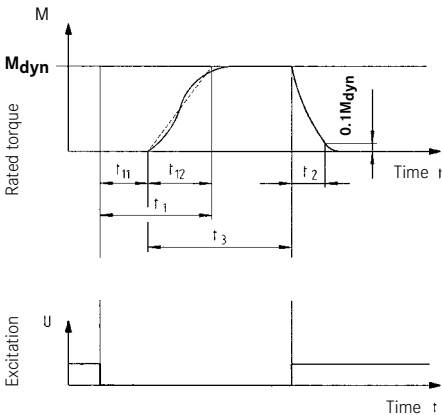
Maximum permissible rotational speed referred on standard friction lining

Operating times

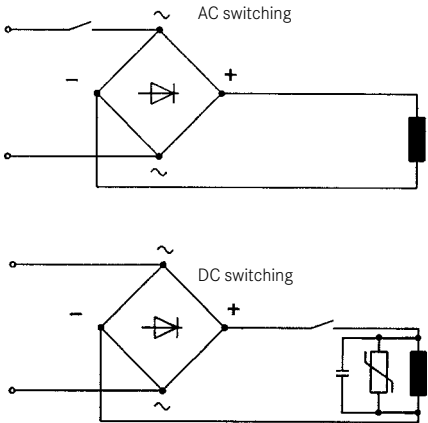
The listed operating times are guide values which apply to DC switching with rated air gap  $s_{Lr}$ , warm coil and standard rated torque. The times

specified are mean values. The engagement time  $t_1$  is approximately 8 to 10 times longer for AC switching.

Torque time rated dependent on excitation voltage



$t_{11}$  = Delay time when connecting  
 $t_{12}$  = Rise time of braking torque  
 $t_1$  = Engagement time  
 $t_2$  = Disengagement time  
 $t_3$  = Slipping time



# Technical data

## Operating times

Size	Rated torque $M_K$ [Nm]	$Q_E$ [J]	$S_{hue}$ [1/h]	Operating times <sup>1)</sup> [ms]			
				$t_{11}$	$t_{12}$	$t_1$	$t_2$
06	4	3000	79	15	13	28	45
08	8	7500	50	15	16	31	57
10	16	12,000	40	28	19	47	76
12	32	24,000	30	28	25	53	115
14	60	30,000	28	17	25	42	210
16	80	36,000	27	27	30	57	220
18	150	60,000	20	33	45	78	270
20	260	80,000	19	65	100	165	340
25	400	120,000	15	110	120	230	390

<sup>1)</sup> The operating times specified relate to the use of INTORQ rectifiers and coils with a supply voltage of 205 V DC

The maximum permissible friction work per switching cycle  $Q_E$  relates to the standard friction lining

## Aluminium rotor design with low rate of wear

The wear values in the table apply to the friction lining with low rate of wear and to the standard rated torque. The friction energies specified up to the point of maintenance

are rough guide values that are subject to a high degree of variation depending on various influencing factors.

Size	06	08	10	12	14	16	18	20	25	
$Q_E$ Maximum permissible friction work per switching cycle [J]										
100 r/min	3000	7500	12000	24,000	30,000	36,000	60,000	80,000	120,000	
1000 r/min	3000	7500	12,000	24,000	30,000	36,000	60,000	80,000	120,000	
1200 r/min	3000	7500	12,000	24,000	30,000	36,000	60,000	80,000	120,000	
1500 r/min	3000	7500	12,000	24,000	30,000	36,000	60,000	24,000	36,000	
1800 r/min	3000	7500	12,000	24,000	30,000	36,000	36,000	on request		
3000 r/min	3000	7500	12,000	24,000	18,000	11,000	on request			
3600 r/min	3000	7500	12,000	7000	on request					
$Q_{BW}$	[10 <sup>6</sup> J]	85	158	264	530	571	966	1542	2322	3522
$S_{hue}$	[h <sup>-1</sup> ]	79	50	40	30	28	27	20	19	15

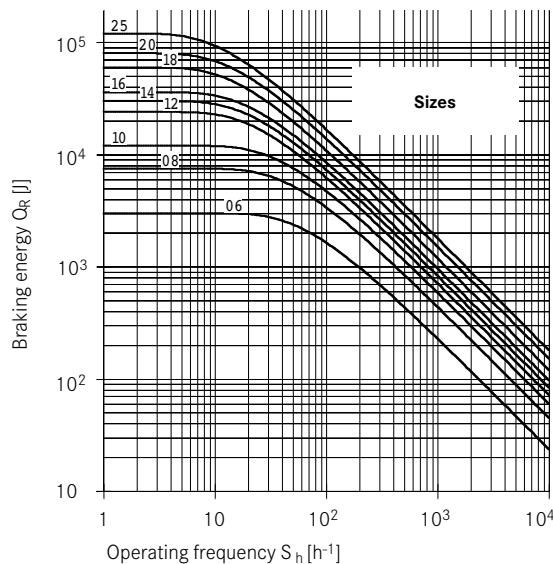
$Q_{BW}$  = Friction energy of brake until maintenance  
 $S_{hue}$  = Transitional operating frequency

In the region of the load limit (operation > 50%  $Q_E$ ) the value for  $Q_{BW}$  can drop as low as 40%

## Technical data

### Service life and wear

#### Friction energy and operating frequency



$$S_{hmax} = \frac{-S_{hue}}{\ln\left(1 - \frac{Q_R}{Q_E}\right)} \quad Q_{smax} = Q_E \left(1 - e^{-\frac{S_{hue}}{S_h}}\right)$$

The maximum permissible operating frequency  $S_{hmax}$  depends on the braking energy  $Q_R$ . The operating frequency  $S_h$  results in the maximum permissible friction work during cyclic switching  $Q_{smax}$ . Higher speed and switching energy values increase wear, because the friction surfaces are briefly subjected to very high temperatures.

#### Maintenance

Brakes are components which are subject to a great deal of wear. When installing the brake, it must be ensured that it can be easily accessed for inspection and maintenance purposes. Intervals between inspections should be set in accordance with the expected service life and load. For more information, please see the operating instructions.

The brake has to be adjusted when  $s_{Lmax}$  is reached. The friction energy to be withstood up to this point is dependent on a number of factors: in particular, the inertias to be braked, the braking speed, the operating frequency and the resulting temperature on the friction surfaces. For this reason, no universal value for all operating conditions can be given in respect of the amount of friction energy that can be handled before adjustment is required. In addition, increased wear should be expected with a vertical brake shaft. The BFK458 can be adjusted when the maximum permissible working air gap is reached ( $s_{Lmax}$ ). The dimensioning of the friction lining allows it to be readjusted at least 5 times.

Where the amount of friction energy per switching operation is low, the brake's mechanical components can impose limitations in terms of service life. In particular, the rotor/hub connection, springs, armature plate and sleeves are subject to operational wear. The expected service life of the standard design is around 1 million load alternations. Solutions that are optimised in terms of service life are available in cases where a longer service life is required (consult the manufacturer).

#### BFK458-L

Guaranteed performance data for the LongLife design

- Guaranteed service life of brake mechanism:
  - 10x10<sup>6</sup> repetitive cycles of operation
  - 15x10<sup>6</sup> reversing cycles of operation
- The brake warranty covers either a period of two years or the guaranteed number of cycles – whichever is reached first.
- The scope of the warranty in the event of premature failure covers replacement of the brake, including a flat-rate replacement fee



## Accessories

### Hand release

The hand release is used to release the brake by hand and can be retrofitted. The hand release springs back to its base position automatically after operation (1). The hand release requires an additional air gap  $S_{HL}$  in order to function; this is factory-set prior to delivery. Dimension  $S_{HL}$  (see the mounting instructions) must be checked once the equipment has been mounted.

Size	$S_{LN} \begin{smallmatrix} +0.1 \\ -0.05 \end{smallmatrix}$ [mm]	$S_{HL} \begin{smallmatrix} +0.1 \\ -0.05 \end{smallmatrix}$ [mm]
06 08 10	0.2	1
12 14 16	0.3	1.5
18 20	0.4	2
25	0.5	2.5

### Flange

A flange can be used if no suitable counter friction face is available. The flange can also be fitted with a cover ring.

### Friction plate

A friction plate is available for sizes 06 up to and including 16. This should be used if the counter face is smooth and machined, but is not suitable as a friction surface. The plate can be combined with a cover ring.



Flange



Friction plate  
(sizes 06 – 16)

### Noise-reduced designs

The noise reduction required in many applications can be achieved in two ways:

#### 1. Impact-noise-reduced armature plate

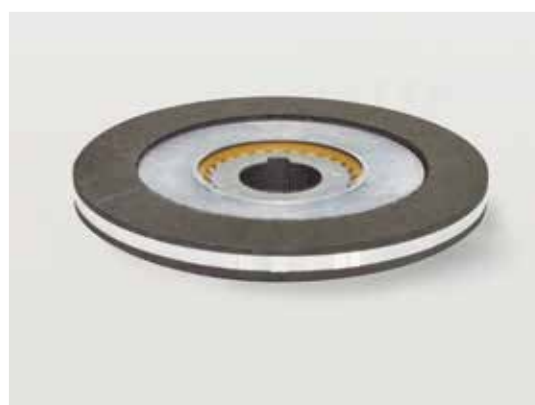
The brake's operating noise can be minimised using special damping elements, which are installed between the pole face and the armature plate as shock absorbers.

#### 2. Noise-reduced aluminium rotor

The rotor with plastic sleeve reduces the rattling noises in the rotor/hub connection. At the same time, this increases the service life of this connection.

### Features and advantages

- Low rate of wear between rotor and hub
- Recommended for frequency inverter operation
- Noise-reduced design
- Also available in combination with CCV



## Accessories

### Seal

To a large extent, the cover ring prevents the exit or ingress of dust, humidity, dirt, etc., out of or into the braking area. The seal is inserted into the groove on the stator. If no suitable groove is available on the counter friction face, we recommend the use of a flange or a friction plate.



Seal

### Connection flange (double brake)

The connection flange can be used to adapt a second basic module to basic module N; the resulting double brake is suitable for use in stage machinery or other applications with increased safety requirements.



Connection flange

### Centring flange (tacho brake)

Basic module N combined with a centring flange is suitable for mounting a tacho generator.

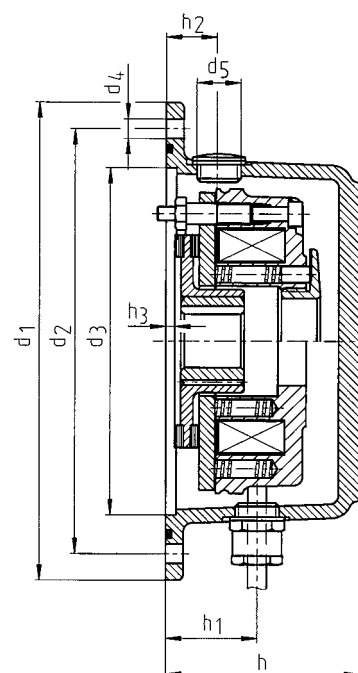


Centring flange

## Accessories

### Brake cover

A brake cover can be mounted onto basic module E and basic module N as an option, to protect the brake from water and dust (degree of protection acc. to IP65). This design is not available in conjunction with a hand release and a flange.



Size	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub> <sup>H8</sup>	d <sub>4</sub>	d <sub>5</sub>	h	h <sub>1</sub>	h <sub>2</sub>	h <sub>3</sub> <sup>1)</sup>
06	135	120	98	4x4.5	M16x1.5	55	28	16.5	3
08	155	142	118	4x5.5	M20x1.5	61	34	20	3
10	185	166	143	4x5.5	M20x1.5	72	39	21	3
12	205	192	163	4x6.6	M20x1.5	82	42	23	3
14	225	212	183	4x6.6	M20x1.5	92	51	24	3
16	250	236	208	4x6.6	M20x1.5	98	52	25	3
18	285	268	238	4x6.6	M20x1.5	115	60	29	3
20	330	314	283	4x9	M20x1.5	131	69	35	3
25	390	368	328	4x9	M20x1.5	142	78	40	3

<sup>1)</sup> Recommended recess length on motor end shield

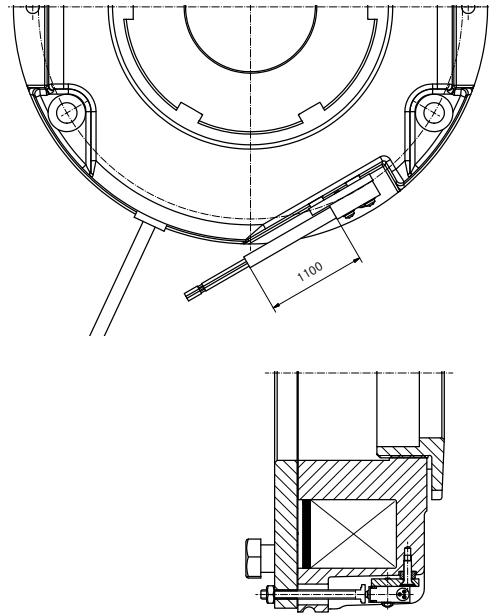
## Accessories

### Microswitch

The brake can be fitted with a microswitch for the purpose of monitoring the release or wear. The microswitch can be built into the circuit as an NC contact or an NO contact.

As of June 2012, a new small microswitch (with UL acceptance) is in use, which is perfectly adapted to the contour of the brake. The old switch design can be converted by connecting an adapter to the same threaded holes.

Mounting the microswitch onto basic module E



### Microswitch for hand release monitoring in combination with basic module N

Gate drives, for instance, are provided with brakes with hand release, and a microswitch for monitoring the hand release. In this case, the hand release must make it possible to move the gate to the desired position in manual operation, e.g. using a crank. This manual operation has to be detected via a microswitch, whose switching signal must be combined with the motor control so that the motor can be prevented from starting (thus also preventing any possible injury to the operator). The microswitch for hand release monitoring is a built-on option.

The fixing bracket is screwed onto the stator via the threaded holes on the rear face. The fixing bracket enables a microswitch to be fastened to it. The two directions of release, towards and away from the motor, can be implemented by using different fixing brackets and microswitch settings.

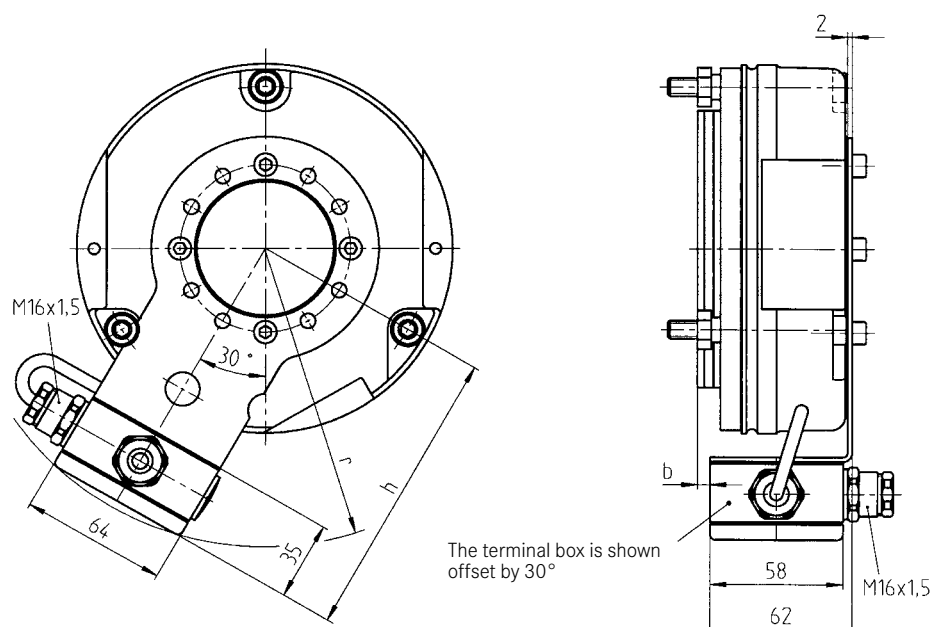


## Accessories

### Terminal box in combination with basic module N

The connecting cables can easily be integrated into higher-level controls via the terminal box (brake sizes 12-25) in order to support different wiring options (total of 3 inputs/outputs). 2/4-pole terminal strips, 4-pole half-wave and bridge rectifiers and a microswitch connection can be integrated into the terminal box at the customer's request.

The terminal box is mounted on the spring-applied brake using a fixing bracket and screws, as shown in the illustration. You can select the mounting angle according to your requirements by using the assembly kit.



Size	12	14	16	18	20	25
b	-5	5.5	12.5	23	37.5	45.5
h	122	130	142	155	174	198
r	126	134	146	158.5	177	201

■ Dimensions in mm



Accessories

Bridge rectifiers and half-wave rectifiers

Type code

B

E

G

-

5

6

1

-

440

Brake

Electronics

Rectifier

1-Bridge rectifier

2-Half-wave rectifier

5-Bridge/half-wave rectifier

4-pole

6-pole

1-Mounting position horizontal

2-Mounting position vertical

3-Mounting position horizontal with snap-in stud

440 Voltage 440 V AC

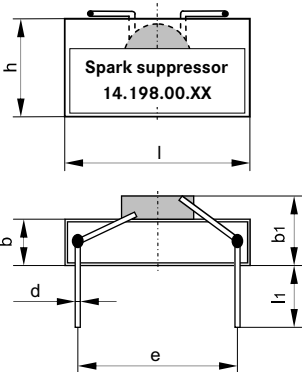
INTORQ 14.198.00 universal spark suppressor

The universal spark suppressor limits the induced voltage arising when inductive direct current consumers are switched off on the DC side. These induced voltages can damage coils and switches. VDE 0580 therefore requires

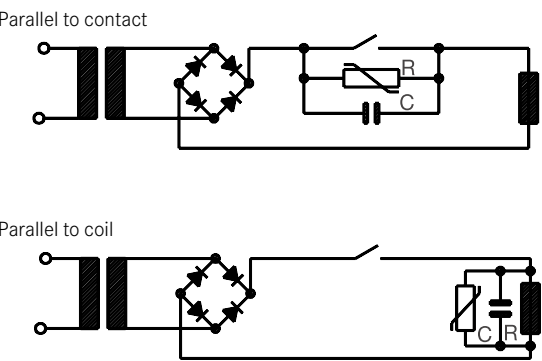
that, in order to avoid impermissibly high switch-off voltages and overvoltages, suitable protective measures must be provided by the user. The universal spark suppressor is available in 4 versions for the following voltage ranges:

INTORQ	Coil voltage [V DC]	Max. connection voltage	Max. coil power [W]	Capacitor- voltage	b	b <sub>1</sub> approx.	d	e approx.	h	l	I <sub>1</sub> approx.	m [g]
14.198.00.01	24 – 50	60 V~	110	250 V~	7	11	0.7	20	17	26.5	16	7
14.198.00.02	50 – 120	250 V~	110	630 V~	15	19	0.7	22.5	25	31.5	12	22
14.198.00.03	120 – 200	400 V~	110	1000 V~	8.5	15	0.7	20	19	26.5	16	17
14.198.00.04	200 – 250	555 V~	110	1000 V~	8.5	15	0.7	20	19	26.5	16	10

Dimensions



Wiring example

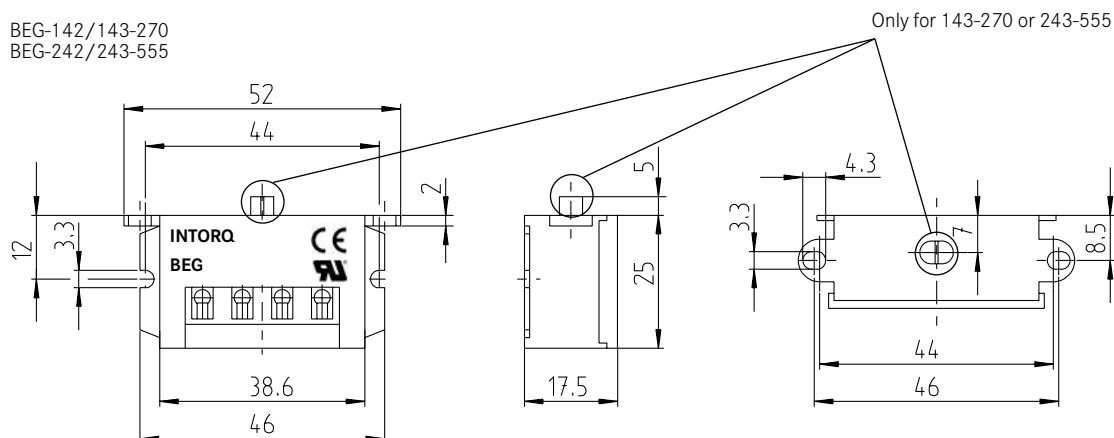


# Accessories

## Bridge rectifiers and half-wave rectifiers, 4-pole

### Dimensions

BEG-142/143-270  
BEG-242/243-555



### Bridge rectifiers, 4-pole

BEG-142-270 vertical mounting position  
BEG-143-270 horizontal mounting position with snap-in stud

### Half-wave rectifiers, 4-pole

BEG-242-555 vertical mounting position  
BEG-243-555 horizontal mounting position with snap-in stud

### Application area

Current supply for spring-applied brakes from AC mains (normal excitation)  
Example: 205 V DC coil on 230 V AC mains

### Application area

Current supply for spring-applied brakes from AC mains (normal excitation)  
Example: 180 V DC coil on 400 V AC mains

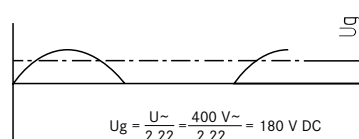
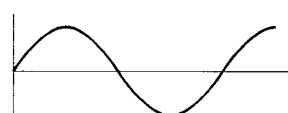
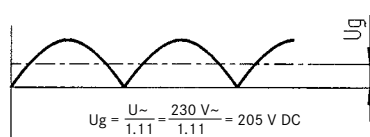
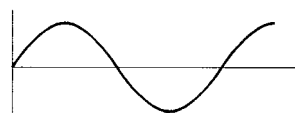
### Technical data

Max. supply voltage 270 V~  
Max. DC current at 60°C 1.0 A  
Max. ambient temperature -25°C to +80°C  
For the selection of associated coil voltages, please refer to the table

### Technical data

Max. supply voltage 555 V~  
Max. DC current at 60°C 1.0 A  
Max. ambient temperature -25°C to +80°C  
For the selection of associated coil voltages, please refer to the table

The rectifiers are protected against overvoltage by input and output varistors.

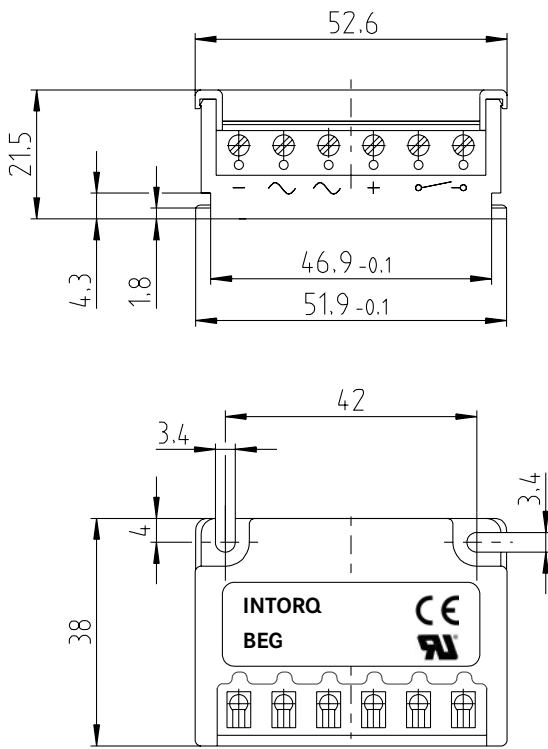


The rectifiers are protected against overvoltage by input and output varistors.

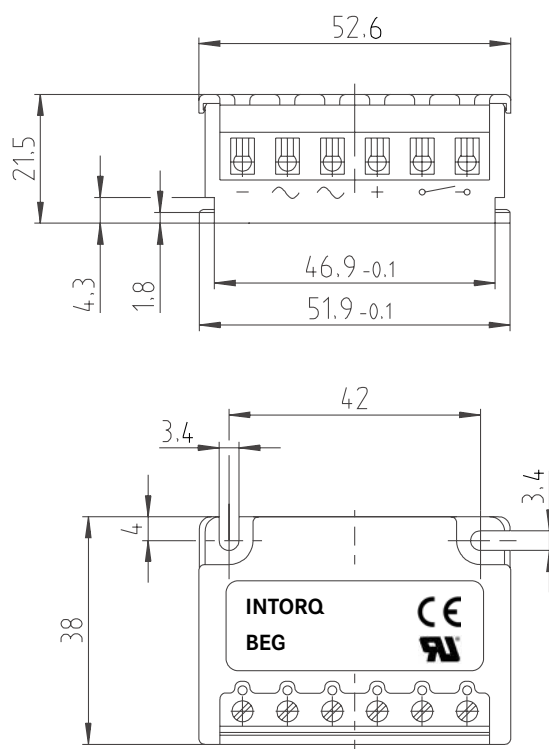
# Accessories

## Bridge rectifiers, 6-pole Dimensions

BEG-162-270



BEG-161-270



### Bridge rectifiers, 6-pole

BEG-1 62-270 vertical mounting position  
BEG-1 61-270 horizontal mounting position

### Application area

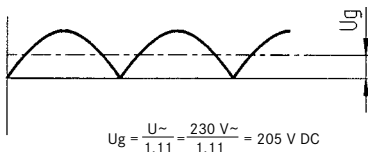
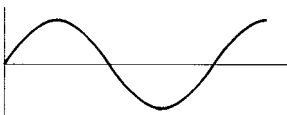
Current supply for spring-applied brakes from AC mains (normal excitation)  
Example: 205 V DC coil on 230 V AC mains

### Technical data

Max. supply voltage 270 V~  
Max. DC current at 60°C 0.75 A  
Max. ambient temperature -25°C to +80°C

The rectifiers are protected against overvoltage by input and output varistors.

BEG-162-270/161-270/  
262-460/261-460 rectifiers also contain the required spark suppressor.  
For the selection of associated coil voltages, please refer to the table

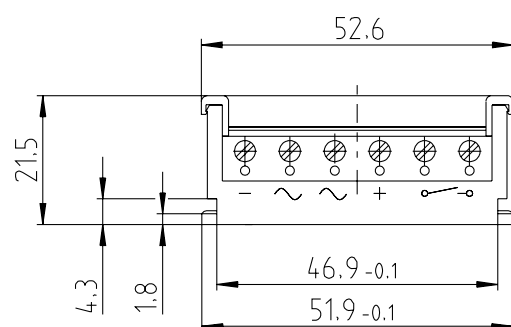


# Accessories

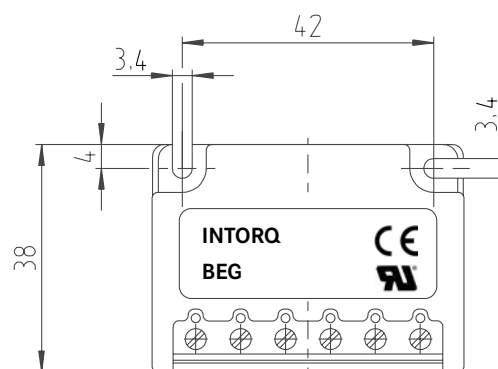
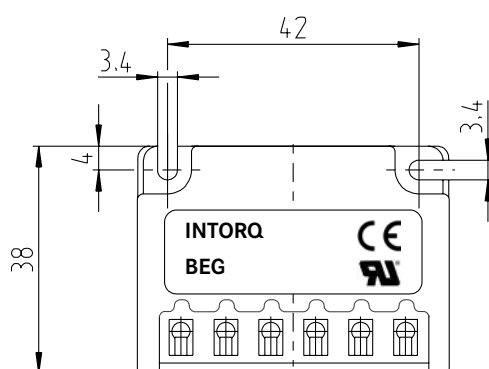
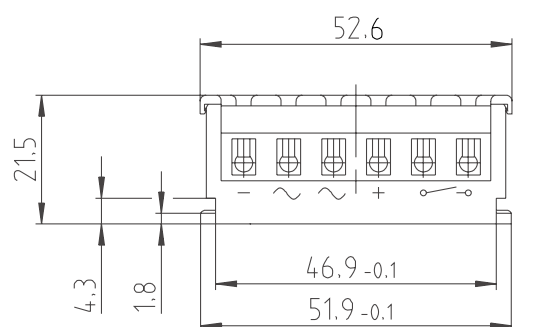
## Half-wave rectifiers, 6-pole

### Dimensions

BEG-262-460  
BEG-262-555



BEG-261-460  
BEG-261-555



### Half-wave rectifiers, 6-pole

BEG-262-460 vertical mounting position

BEG-261-460 horizontal mounting position

BEG-262-555 vertical mounting position

BEG-261-555 horizontal mounting position

### Application area

Current supply for spring-applied brakes from AC mains (normal excitation)

Example: 180 V DC coil on 400 V AC mains

### Technical data

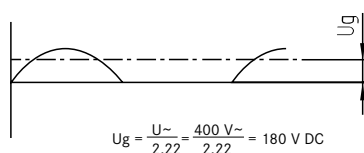
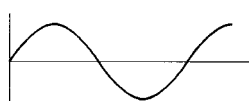
Max. supply voltage 460 V~ / 555 V~

Max. DC current at 60°C 0.75 A

Max. ambient temperature -25°C to +80°C

The rectifiers are protected against overvoltage by input and output varistors. BEG-162-270/161-270/262-460/261-460 rectifiers also contain the required spark suppressor.

For the selection of associated coil voltages, please refer to the table



Accessories

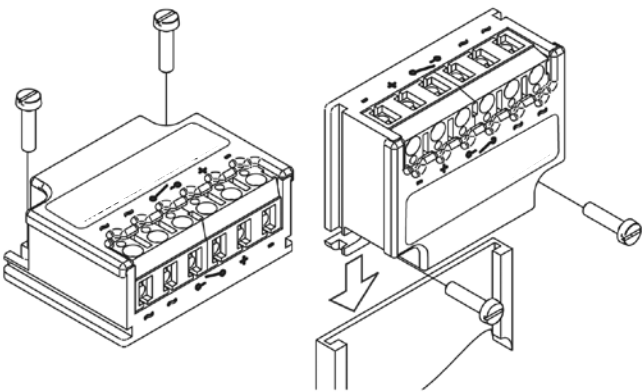
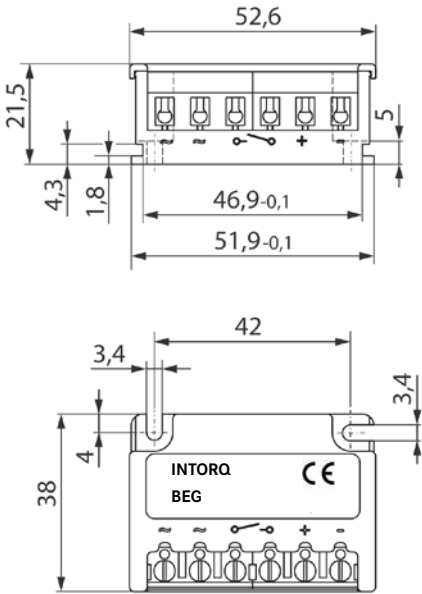
Bridge/half-wave rectifier

Once a set overexcitation time has elapsed, the bridge/half-wave rectifiers switch from bridge rectification to half-wave rectification.

This makes it possible to improve switching performance or reduce power in accordance with coil dimensioning.

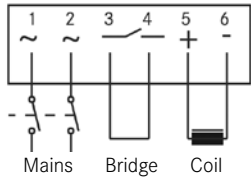
Rectifier type	Supply voltage	Overexcitation		Holding current reduction	
	[V AC]	Coil voltage [V DC]	Size	Coil voltage [V DC]	Size
BEG-561-255-030	230	103	06 to 25	205	06 to 14
BEG-561-255-130					16 to 25
BEG-561-440-030-1	400	180	06 to 25		–

The information in this table is valid for the BFK458 with standard rated torque and for designs without pole shim (assignment for other brakes on request)

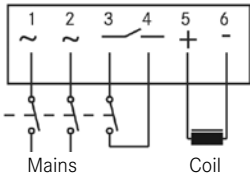


Connection diagrams

AC switching



DC switching



Technical data

Rectifier type	
Output voltage with bridge rectification	0.9xU1
Output voltage with half-wave rectification	0.45xU1
Ambient temperature (storage/operation) [°C]	-25 to +70

In the case of switching on the DC side (fast engagement), switching must also occur on the supply side. Otherwise, overexcitation will not occur on restarting.

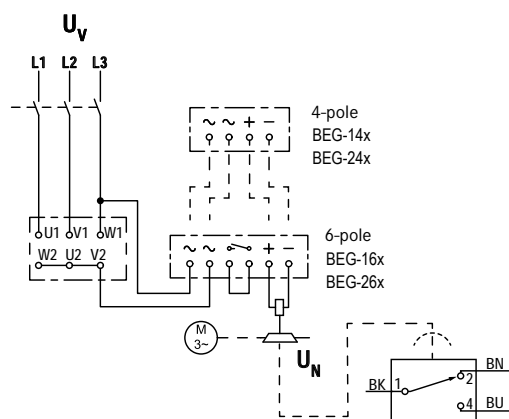
Type	Input voltage U1 (40 Hz to 60 Hz)			Max. current I <sub>max</sub> .		Overexcitation time t <sub>0</sub> (±20%)		
	min [V~]	Rated [V~]	max [V~]	Bridge [A]	Half-wave [A]	at U 1 min [s]	at U 1 Rated [s]	at U 1 max [s]
BEG-561-255-030 BEG-561-255-130	160	230	255	3.0	1.5	0.430	0.300	0.270
						1.870	1.300	1.170
BEG-561-440-030-1	230	400	440	1.5	0.75	0.500	0.300	0.270



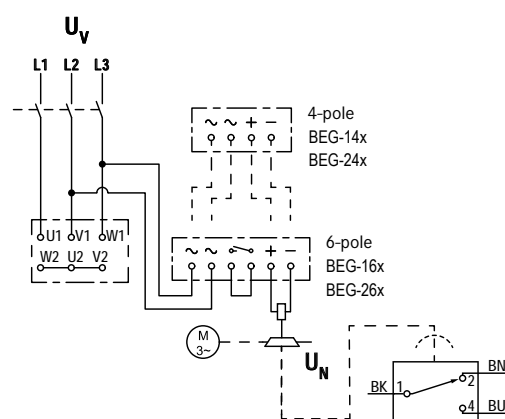
# Accessories

## Connection diagrams

### AC switching parallel to the motor – strong delayed engagement

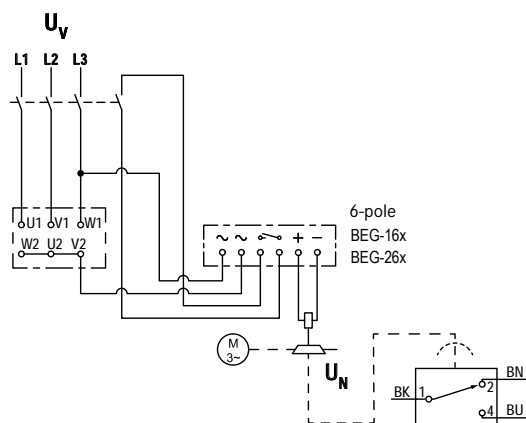


Supply: Phase-Starpoint

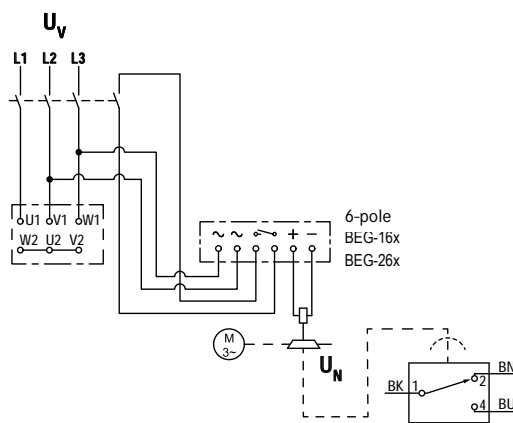


Supply: Phase-Phase

### DC switching parallel to the motor – fast engagement



Supply: Phase-Starpoint

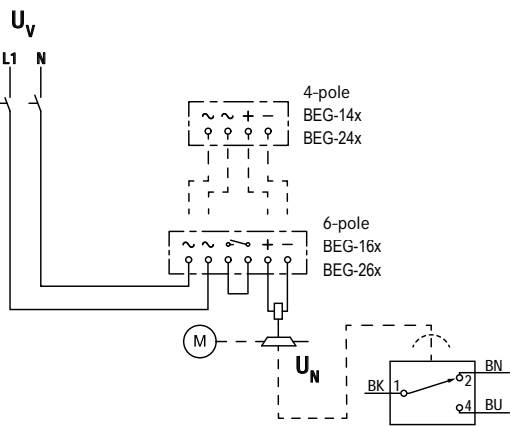


Supply: Phase-Phase

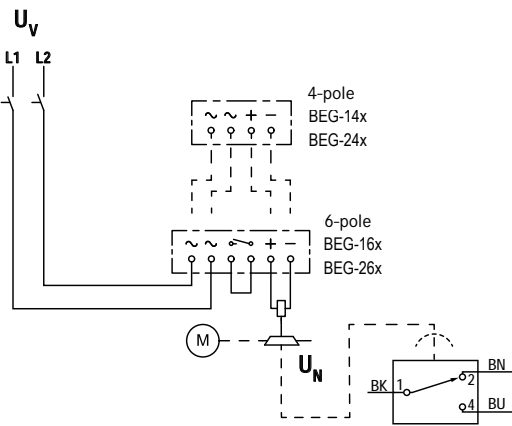
# Accessories

## Connection diagrams

### AC switching by mains – delayed engagement

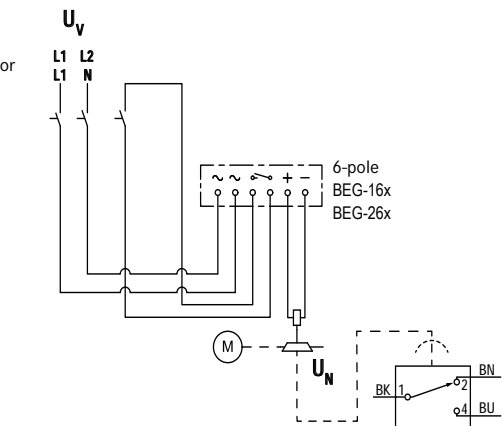


Supply: Phase-N

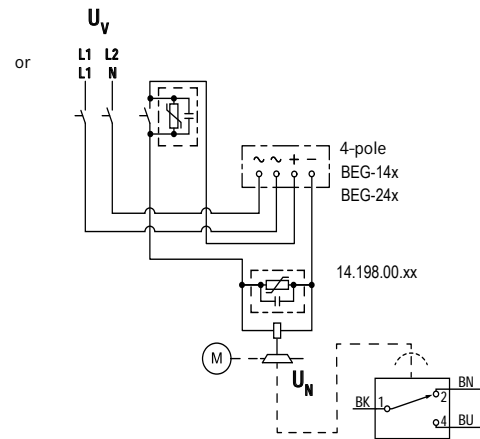


Supply: Phase-Phase

### DC switching by mains – fast engagement



Supply: Phase-Phase or Phase-N by 6-pole rectifier



Supply: Phase-Phase or Phase-N by 4-pole rectifier

# Accessories

## Supply voltage selection table for bridge rectifiers and half-wave rectifiers

### Rectifier type and rated coil voltage for mains voltage

AC voltage V AC	Rectifier	Rectifier type 4-pole 1 A at 60°C	Spark suppressor	Rectifier type 6-pole 0.75 A at 60°C	Rated coil voltage ± 10% V DC
42 V	Half-wave	BEG-243/242-555	14.198.00.01	BEG-262/261-460	20 V
48 V	Bridge Half-wave	BEG-142/143-270 BEG-243/242-555	14.198.00.01 14.198.00.01	BEG-162/161-270 BEG-262/261-460	42 V 20 V
110 V	Bridge	BEG-142/143-270	14.198.00.02	BEG-162/161-270	103 V
220 V	Bridge Half-wave	BEG-142/143-270 BEG-243/242-555	14.198.00.04 14.198.00.02	BEG-162/161-270 BEG-262/261-460	205 V 103 V
230 V	Bridge Half-wave	BEG-142/143-270 BEG-243/242-555	14.198.00.04 14.198.00.02	BEG-162/161-270 BEG-262/261-460	205 V 103 V
240 V	Bridge Half-wave	BEG-142/143-270 BEG-243/242-555	14.198.00.04 14.198.00.02	BEG-162/161-270 BEG-262/261-460	215 V 103 V
255 V	Bridge	BEG-142/143-270	14.198.00.04	BEG-162/161-270	225 V
277 V	Half-wave	BEG-243/242-555	14.198.00.03	BEG-262/261-460	127 V
290 V	Half-wave	BEG-243/242-555	14.198.00.03	BEG-262/261-460	127 V
380 V	Half-wave	BEG-243/242-555	14.198.00.03	BEG-262/261-460	180 V
400 V	Half-wave	BEG-243/242-555	14.198.00.03	BEG-262/261-460	180 V
415 V	Half-wave	BEG-243/242-555	14.198.00.03	BEG-262/261-460	180 V
420 V	Half-wave	BEG-243/242-555	14.198.00.03	BEG-262/261-460	180 V
440 V	Half-wave	BEG-243/242-555	14.198.00.04	BEG-262/261-460	205 V
460 V	Half-wave	BEG-243/242-555	14.198.00.04	BEG-262/261-460	205 V
480 V	Half-wave	BEG-243/242-555	14.198.00.04	BEG-262/261-555	215 V
500 V	Half-wave	BEG-243/242-555	14.198.00.04	BEG-262/261-555	225 V
555 V	Half-wave	BEG-243/242-555	14.198.00.04	BEG-262/261-555	250 V

\* Spark suppressor without capacitor. For optimum spark suppression, we recommend the use of spark suppressor 14.198.00.04

Max. rated coil voltage: 250 V  
Standard rated voltages: 24, 96, 103, 170, 180, 190, 205 V

## Dimensioning

### Basics

A brake is dimensioned essentially on the basis of the required braking torque  $M_{\text{erf}}$ .

The inertias to be braked (moments of inertia), the relative speeds, the braking times and the operating frequencies also have to be considered in the calculations. Marginal conditions, such as ambient temperature, air humidity, dust and mounting position should be known. In the event of extreme/critical operating conditions, please consult the manufacturer. The brake is dimensioned in accordance with VDI guideline 2241.

**Friction surfaces must always be kept free of oil and grease.**

For explanations of the terms used in the calculation, please refer to the list of abbreviations on page 5.

### Safety factor

To ensure the necessary transmission security even under extreme operating conditions, braking torque need to include the safety factor  $K$ , the value of which should be set dependent upon the operating conditions.

$$K \geq 2$$

### Load types

The following load types are primarily encountered in practice:

$$M_{\text{erf}} = M_a \cdot K \leq M_K$$

$$M_a = \frac{J_L \cdot \Delta n_0}{9.55 \cdot \left(t_3 - \frac{t_{12}}{2}\right)}$$

$$M_{\text{erf}} = \frac{J_L \cdot \Delta n_0}{9.55 \cdot \left(t_3 - \frac{t_{12}}{2}\right)} \cdot K$$

### Dynamic and static load

Most applications belong to this category, as in most cases there is not only a static torque but also a dynamic load.

$$M_{\text{erf}} = (M_a \pm M_L) \cdot K \leq M_K$$

$$M_{\text{erf}} = \left( \frac{J_L \cdot \Delta n_0}{9.55 \cdot \left(t_3 - \frac{t_{12}}{2}\right)} \pm M_L \right) \cdot K \leq M_K$$

+  $M_L$  = To be used with driving load torque  
(e.g. when lowering a load)

-  $M_L$  = For braking operation

### Estimating the required braking torque and/or size

If only the drive power to be transmitted is known, the required torque or braking torque can be determined as follows:

$$M_{\text{erf}} = 9550 \frac{P}{\Delta n_0} \cdot K \leq M_K$$

### Thermal load

If high operating frequencies and friction energy/switching cycle are to be expected, we recommend recalculating the thermal data for the brake. The friction energy per switching cycle is calculated as follows:

$$Q = \frac{J_L \cdot \Delta n_0^2}{182.5} \cdot \frac{M_K}{M_K \pm M_L}$$

-  $M_L$  = To be used when lowering the load, for example  
+  $M_L$  = For braking operation

The permissible friction energy per switching cycle at a given operating frequency can be taken from the diagrams on page 14. If the friction energy per switching cycle is known, the permissible operating frequency can be taken from the diagrams mentioned above.

# Dimensioning

## Example calculation

The following technical data is known:

$$P = 3 \text{ kW}$$

$$\Delta n_0 = 1450 \text{ rpm}$$

$$J_L = 0.13 \text{ kgm}^2 \text{ total}$$

$$t_3 = 2 \text{ s}$$

$$M_L = 15 \text{ Nm}$$

$$S_h = 100 \text{ switching operations/h}$$

Estimating the required braking torque and/or size

$$M_{\text{erf}} = 9550 \cdot \frac{P}{\Delta n_0} \cdot K$$

$$M_{\text{erf}} = 9550 \cdot \frac{3}{1450} \cdot 2 = 40 \text{ Nm}$$

Assume BFK458-14

Determining the required braking torque

$$M_{\text{erf}} = \left( \frac{J_L \cdot \Delta n_0}{9.55 \cdot \left( t_{12} \cdot \frac{t_{12}}{2} \right)} + M_L \right) \cdot K$$

$$t_{12} = 0.025 \text{ s (see page 14)}$$

$$M_{\text{erf}} = \left( \frac{0.13 \cdot 1450}{9.55 \cdot \left( 2 \cdot \frac{0.025}{2} \right)} + 15 \right) \cdot 2 = 50 \text{ Nm}$$

Therefore, BFK458-14 is chosen.

$$M_K = 60 \text{ Nm} > M_{\text{erf}} = 50 \text{ Nm}$$

## Thermal recalculation

$$Q = \frac{J_L \cdot \Delta n_0^2}{182.5} \cdot \frac{M_K}{M_K \pm M_L}$$

$$Q = \frac{0.13 \cdot 1450^2}{182.5} \cdot \frac{60}{(60 - 15)} = 1997 \text{ J}$$

Calculated switching energy  $Q = 1997 \text{ J/switching cycle}$ .

The diagram on page 18 shows a max. permissible friction work of 7,326 J for size 14 at  $S_h = 100 \text{ h}^{-1}$ .

$$Q = 1997 \text{ J} < Q_{\text{Smax}} = 7326 \text{ J}$$

The brake is correctly dimensioned.

## Example order

Brake type BFK458-14E or design N (with or without torque adjustment ring) is required, with additional hand release and seal ring.

Supply voltage 205 V =, shaft diameter 25 mm.

BFK458-14E, 205 V =, d = 25 mm

## Product overview

### BFK458 spring-applied brake

INTORQ BFK458-□□□

Size	<input type="checkbox"/> 06	<input type="checkbox"/> 08	<input type="checkbox"/> 10	<input type="checkbox"/> 12	<input type="checkbox"/> 14	<input type="checkbox"/> 16	<input type="checkbox"/> 18	<input type="checkbox"/> 20	<input type="checkbox"/> 25
Design	<input type="checkbox"/> E (with torque adjustment ring)			<input type="checkbox"/> N (without torque adjustment ring)					
Voltage	<input type="checkbox"/> 24 V	<input type="checkbox"/> 96 V	<input type="checkbox"/> 103 V	<input type="checkbox"/> 170 V	<input type="checkbox"/> 180 V	<input type="checkbox"/> 190 V	<input type="checkbox"/> 205 V		
Braking torque	1.5 – 600 Nm (see torque graduations)								
Cable length	<input type="checkbox"/> Standard from 100 mm – 1000 mm in 100 mm steps, from 1000 mm – 3000 mm in 250 mm steps								
Hand release	<input type="checkbox"/> Mounted			<input type="checkbox"/> As mounting kit					
Armature plate	<input type="checkbox"/> Standard		<input type="checkbox"/> Hard chrome-plated (size 06 and above)				<input type="checkbox"/> Noise-reduced (O-ring design)		
	<input type="checkbox"/> With pole shim/brass film								
Microswitch	<input type="checkbox"/> Switching function monitoring (size 12 and above)								
	<input type="checkbox"/> Wear monitoring (size 12 and above)								
	<input type="checkbox"/> Hand release monitoring, direction of release away from motor (sizes 06-25)								
	<input type="checkbox"/> Hand release monitoring, direction of release towards motor (sizes 06-10)								
Terminal box	<input type="checkbox"/> Mounted (size 12 and above)								
Temperature resistance -40 °C	<input type="checkbox"/> With hard chrome-plated friction surfaces (armature plate and flange are essential)								
	<input type="checkbox"/> With temperature-resistant fixing screws								
Rotor	<input type="checkbox"/> Aluminium			<input type="checkbox"/> Noise-reduced (rotor with toothed intermediate ring)					
Rotor with low rate of wear	<input type="checkbox"/> Aluminium			<input type="checkbox"/> Noise-reduced (rotor with toothed intermediate ring)					
Hub	For bore diameter, see Dimensions								
Fixing screw set	<input type="checkbox"/> For mounting onto the flange								
	<input type="checkbox"/> For mounting onto the motor/friction plate								
	<input type="checkbox"/> For flange with through hole (up to and including size 16)								
	<input type="checkbox"/> For connection flange/double brake								
Terminal box	<input type="checkbox"/> As mounting kit								
Counter friction face	<input type="checkbox"/> Friction plate (up to and including size 16)				<input type="checkbox"/> Tacho flange				
	<input type="checkbox"/> Flange				<input type="checkbox"/> Connecting flange double brake				
	<input type="checkbox"/> Flange hard chrome-plated								
Sealing	<input type="checkbox"/> Seal			<input type="checkbox"/> Shaft sealing ring (shaft diameter on request)					
	<input type="checkbox"/> Cap			<input type="checkbox"/> Brake cover					

### Electrical accessories

<b>Bridge rectifier</b>	<input type="checkbox"/> 4-pole without snap-in stud	<input type="checkbox"/> 4-pole with snap-in stud
	<input type="checkbox"/> 6-pole vertical, integrated spark suppressor	<input type="checkbox"/> 6-pole horizontal, integrated spark suppressor
<b>Half-wave rectifier</b>	<input type="checkbox"/> 4-pole without snap-in stud	<input type="checkbox"/> 4-pole with snap-in stud
	<input type="checkbox"/> 6-pole vertical, integrated spark suppressor	<input type="checkbox"/> 6-pole horizontal, integrated spark suppressor
<b>Spark suppressor</b>	<input type="checkbox"/> Yes	

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